



**TRUSTED
AUTONOMOUS
SYSTEMS**
DEFENCE CRC

Current Initiatives & Opportunities

Prof. Jason Scholz

jason.scholz@tasdcrc.com.au

CEO Trusted Autonomous Systems

Innovation Professor (Defence), RMIT University



info@tasdcrc.com.au



www.tasdcrc.com.au

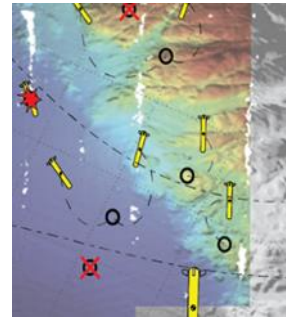


Queensland Government



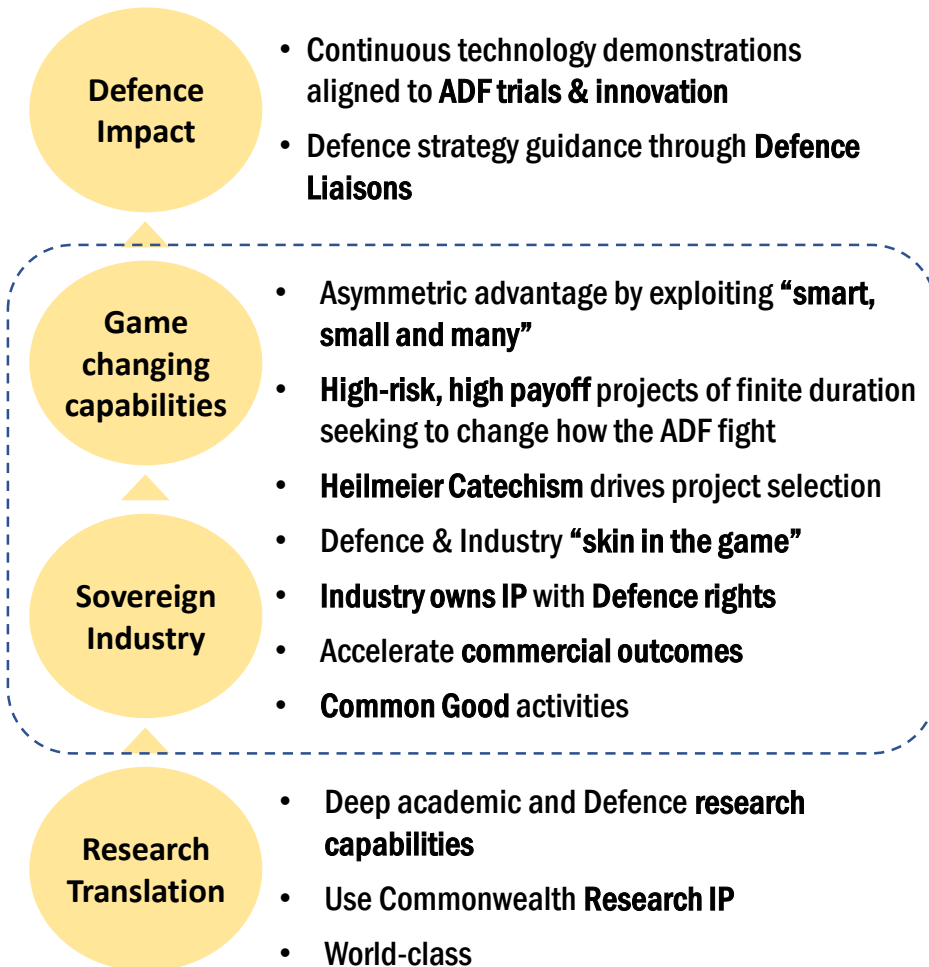
What is TAS?

- Trusted innovation leader & broker of industry & research for the ADF
- A Defence initiative to leverage strong commercial technology drivers, solve the long-term challenges experienced by the Department to deliver targeted, agile, risk-taking, non-competitive, fast engagement with a view to pull forward game-changing technologies needed by the ADF.
- Not for profit, limited by guarantee, board-governed
- Announced July 2017, company started mid-2018
- Commonwealth NGTF, Queensland gov, Direct ADF funded



TAS Purpose

- Advance trusted autonomous systems technologies for asymmetric advantage so the ADF can fight and win
- Create & foster game-changing research, of world standing, that pushes theoretical & practical boundaries of future trusted autonomous systems
- Deliver autonomous systems & robotics technology with clear translation into deployable defence programs & capabilities for Australian Defence
- Build an environment in which Australian industry has the capacity & skills to deliver complex autonomous systems both to Australian Defence & as integral members of the global defence supply chain



Asymmetric Advantage (Air examples)

TAS will enhance
not replace
capability

Enabled by...

Human Machine
Teaming

Sovereign
Common Control
System

Spectrum
Agility

*Images are for
illustrative
purposes only*

Potent manned & optionally-
manned platforms

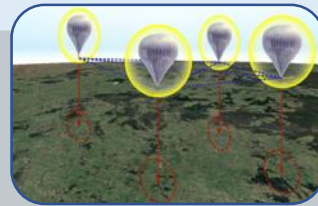


Complex, Large & Few

Autonomous &
unmanned

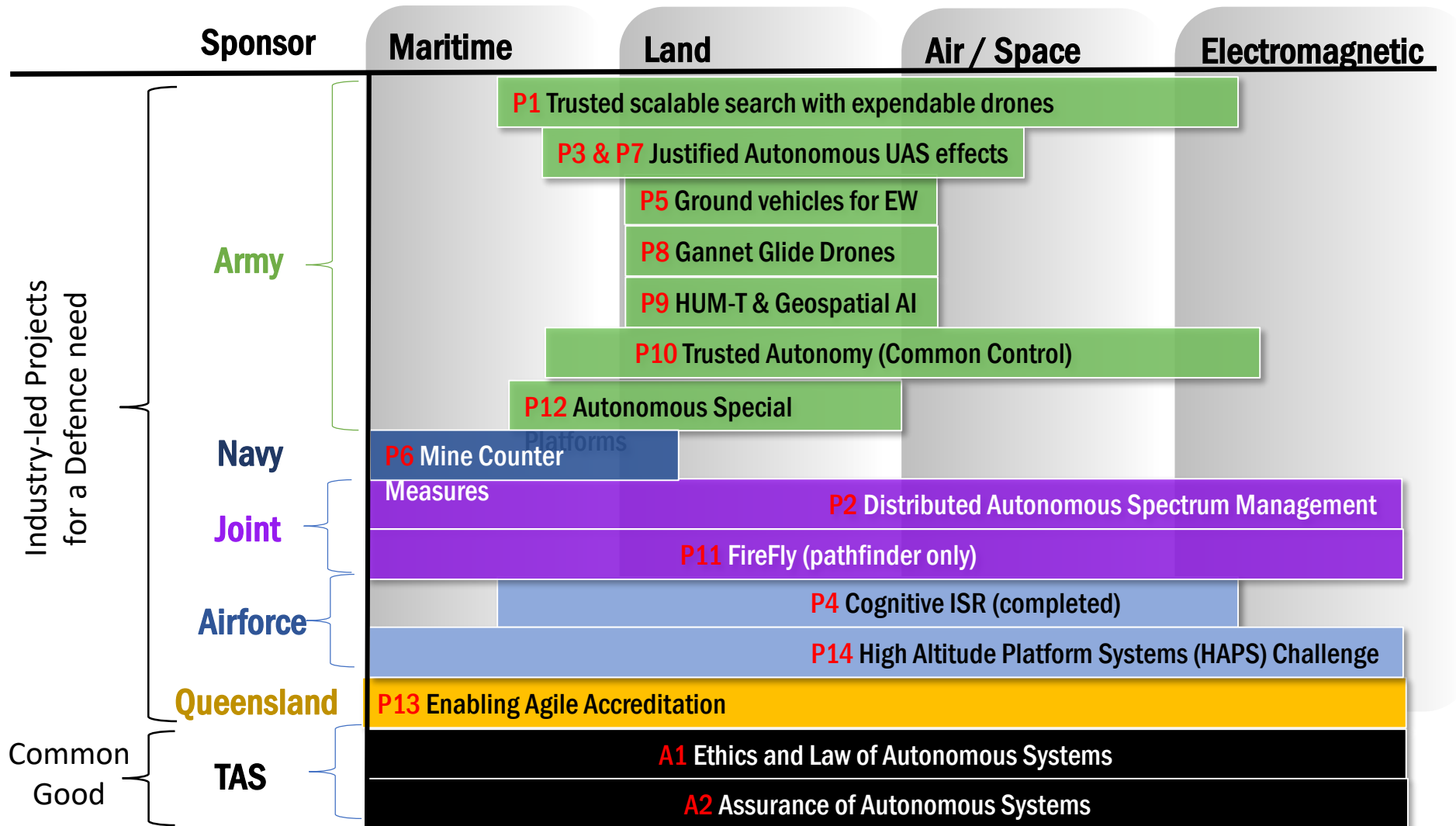


Autonomous, attritable,
flexible, low-cost mass



Smart, Small & Many

Asymmetric
Manoeuvre



TAS will enhance
not replace
capability

Enabled by...

Human Machine
p9 Teaming

Sovereign
Common Control
P10 System

Spectrum
P2 Agility

Images are for
illustrative
purposes only

Foreign/Multi- national Primes

Potent manned platforms
& dismounted combatants



Complex, Large & Few

Sovereign + O/S Primes in Australia

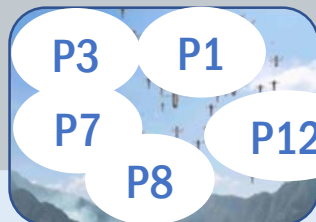
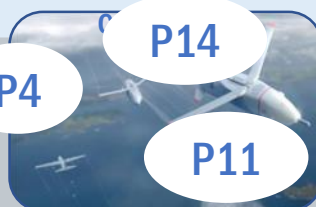
Autonomous, Unmanned
& optionally-manned



Smart, Small & Many

Sovereign SMEs

Autonomous,
attritable, flexible, low-



A1

Asymmetric
Manoeuvre

A2
P13

P4

P14

P11

P6

P5

P3

P1

P7

P8

P12

Example – P4 Cognitive ISR

Scope

- High levels of team autonomy to enable tasking versus control
- Dynamic mitigation of mission impediments eg. task failure or external threats
- On board target detection through image processing
- Machine Vision training utilising synthetic environments

Execution

- Created digital twin environment for synthetic development and testing
- Full virtual capability demonstration using Hardware in the Loop (HWIL) components
- Successful real world end to end demonstration

Future development

- Extend the capability & adaptability of the Behaviour tree-based autonomy
- Further exploration of development & integration of mitigation capabilities
- Extend & refine onboard image processing
- Shorten the Machine Learning training cycle to meet real world timelines



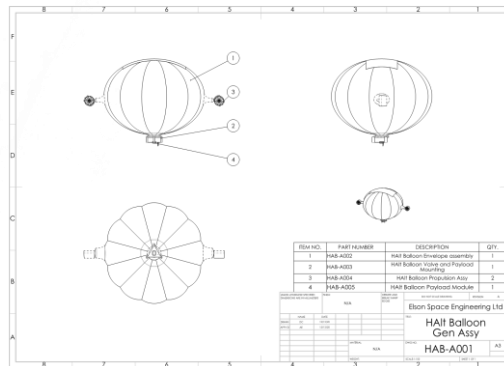
Example – P11 High Altitude Balloon Constellation

VALUE

- **Runway independent delivery of Air Power**
- **Sovereign capability with local supply chains**
- **Agile payload development opportunity**
- **Persistence and satellite-like capabilities** launched at time and place of our choosing in hours/days not months/years for CubeSats
- Payloads can be modified and relaunched (vs satellites)
- **Low cost and expendable/”attritable”** for contested ops
- **Edge intelligence**, multi-sensor, heterogenous sensing capabilities
- **Strategic deployment** (launch in one theatre, user in another)
- **Pre-qualify CubeSats for space**

APPLICATIONS

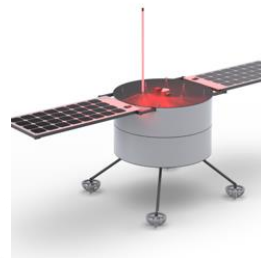
- “FireFly Pathfinder” Emergency Services – Bushfire Intelligence, autonomous detection, fuel load measurement, recovery support, comms relay
- “FireFly Phase 2” – Operational surveillance, deployed force communications, robust PNT, payload delivery, other applications
- Other applications – Search and rescue, marine environmental monitoring



Elson Self-propelled assembly



Danfield 'Pebble' in flight



LUX gondola

Opportunity: High Altitude Pseudo Satellite (HAPS) Challenge

Stimulating and supporting Australian sovereign industry development of a HAPS capability with accurate **station-keeping**, **stable payload control** and **long-endurance flight** at low cost

“This challenge is an exciting new way to contribute to Australia’s security and defence”
GPCAPT Bearman, Air Warfare Centre

Open to Australian based businesses and Australian research organisations



Further information:

www.rmit.edu.au/defence-aerospace/haps-challenge



Opportunity: Sovereign “Common Control”

Purpose: Achieve multiple, simultaneous kill-chain options

Outcome: Poses dilemmas on enemy to counter them all

AUS Ubiquitous Command and Control
(Lambert, Scholz 1999, 2005, 2007)

Common Control Language

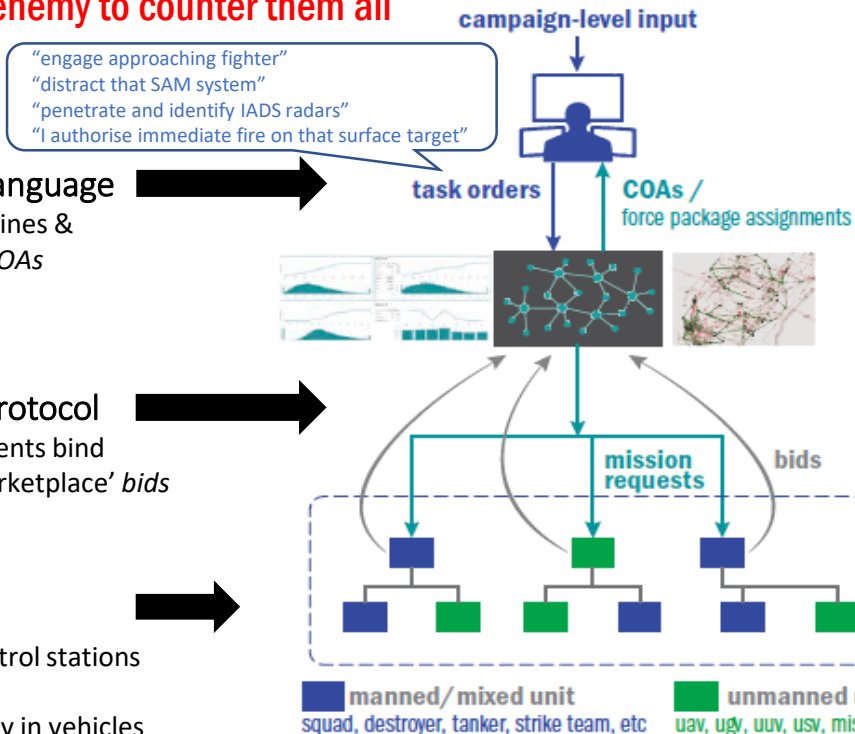
Commanders *task* machines &
(explainable) AI offers COAs

Common Control Protocol

Electronic legal agreements bind
mission requests to ‘marketplace’ *bids*

Bridges & Agents

Surface proprietary control stations
for common control.
Uses available autonomy in vehicles
and controls sensors & effectors



Human command

- develop operational plans
- craft task orders
- identify marketplace of capabilities

Machine-assisted control

- issues request for bids to accomplish task orders
- constructs kill chain sets from available capabilities

Manned and unmanned units available for tasking

- capabilities bid on orders
- quality of bid depends on ability to contribute to an effective kill chain (i.e. proximity, speed, material condition, key functions, success likelihood, efficiency of capability)
- nominate and refine execution tactics

Common Spectrum Management Protocol

Common-good Activities

Facets of Ethical AI in Defence



RESPONSIBILITY

Who is responsible for AI?



GOVERNANCE

How is AI controlled?



TRUST

How can AI be trusted?



LAW

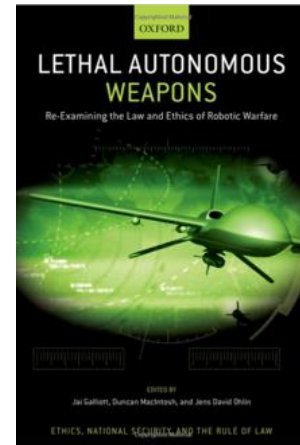
How can AI be used lawfully?



TRACEABILITY

How are the actions of AI recorded?

- **Building trust** in Robotic, AI, C2 and HUM-T systems with autonomy
- **Regulatory** – National accreditation support for industry. Identify gaps in processes, capture new knowledge, best practice, develop new standards, V&V
 - Air - demonstrate safe Detect and Avoid (DAA) at Queensland test range (CASA, FAA, Industry)
 - Maritime - small USVs (SEA1905, AMSA), New course launched for marine surveyors with AIMS
- **Legal** – LAWS CCW GGE, Article 36 reviews, legal status of uncrewed aerial & vessels, liability, export controls, ...
- **Ethics** – Aligning RAS-AI with Defence values, National level policy, Advice on ethics by design, ...
 - “AI Ethics for Defence” (with DSTG & Jericho)



Conclusion

- Described current initiatives in Trusted Autonomous Systems
- Outlined a future of “smart, small and many” to achieve ADF RAS-AI Concepts and Strategies
- TAS complements Jericho’s focus on ‘innovation-to-capability’
- TAS achievements:
 - 14 projects, 2 activities established *fast* with >\$250m total commitments
 - Successful external review by team chaired by Prof Ian Chubb
 - Established several pathways for industry transition to ADF projects
- Accepting game-changing proposals that fit ADF needs
- Stay in touch!
 - Defence-only project and activity updates
 - Defence, industry and academia weekly news

Defence
Impact

Game
changing
capabilities

Sovereign
Industry

Research
Translation



HIGH ALTITUDE AEROSPACE



Join us at...

'Accelerating Trusted Autonomous Systems' Symposium

Townsville + online
20-22 April 2021

<https://tasdcrc.com.au/symposium2021/>



**TRUSTED
AUTONOMOUS
SYSTEMS**
DEFENCE CRC

info@tasdcrc.com.au

